





Introduction TNO Under Water Warfare (UWW) "the Wonderful World Underwater"









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TNO Organisation

- TNO was founded by law in 1932
- Defence Physics Lab established by Ministry of War in 1927 in The Hague, later merged with TNO
- TNO is independent of public & private interests
- Development and application of innovative knowledge
- Clients: Government, Companies and Public organisations
- > 3511 employees
- Total Turnover 563,8 M€ (2010)
- 369,0 M€ Market turnover (2/3 domestic, 1/3 foreign)
- 194,8 M€ Government funding

Source: TNO annual review 2010















Example of early work: experimental listening device for the acoustic detection of aircraft, developed by Groot and van Soest in 1929. The device was developed after testing other available devices from that period, and had better bearing resolution because the sound could reach the ear of the operator undistorted.

Source: http://www.museumwaalsdorp.nl/en/airacous.html







Themes and innovation areas









Defence, Safety and Security theme

Innovation area

Defence research

Innovation area

Safety and security research

Business line

- Cost-effective operations
- Information superiority
- > Force protection
- Human effectiveness

Business line

- National and urban safety and security
- Effective safety and security operations







Military Information Superiority - MIST

- At a time of widespread reduction in available manpower, the need for and availability of information are increasing exponentionally.
- Based on our technological expertise and knowledge about the defence domain, TNO is able and has the ambition to support defence forces in four core areas:
 - EM Sensors
 - EM spectrum control EMSC
 - Situational Awareness Information and IntelligenceUnderwater Warfare UWW







Information Superiority Four "primary" subjects – tracks

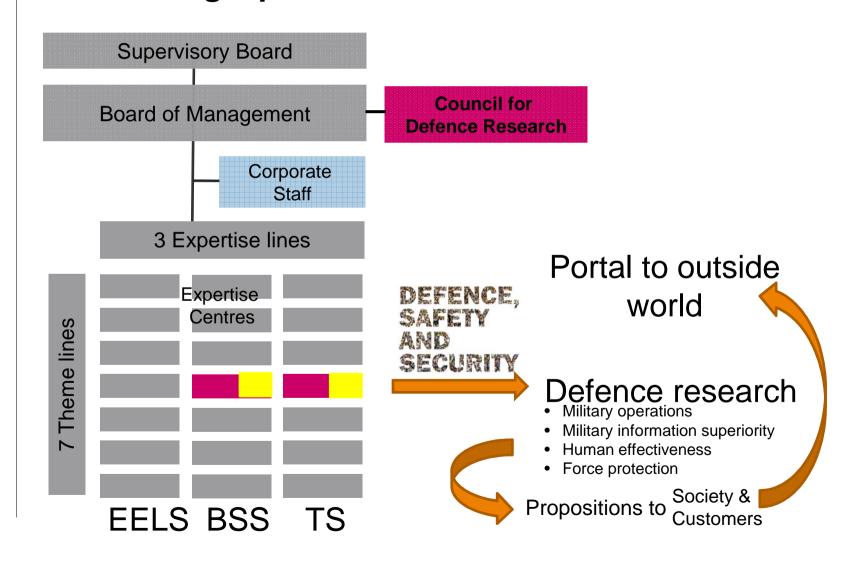
- EMSC EM Spectrum Control
 Yolanda Rieter-Barrell Stefan Vossen
- SA&I2 Situation Awareness Information Intelligence
 Jasper Lindenberg Arthur Smith
- EMSensSys EM Sensor SystemsFrank van de Bogaard Ronald van Waard
-) UWW Underwater WarfareGuus Beckers Ton van Koersel







TNO Strategic partner for NL MOD



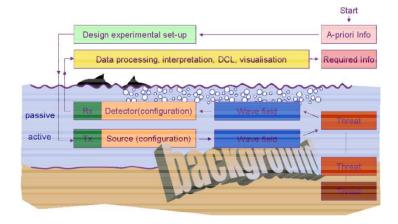






Sonar expertise at TNO

- To design, realize and test passive and/or active sonar systems for application in anti-submarine warfare, mine counter measures and torpedo defense
- To be a supplier of innovative underwater technology systems in cooperation with international industrial partners.
- To be a trusted partner of the Royal Netherlands Navy and offer them consultancy services in their role as smart specifier, smart buyer and smart user of underwater technology.
- > We concentrate on the following three sub-technologies or areas of expertise:
 - underwater systems
 - underwater environment
 - underwater threats.



Each sonar system consists of (many of) the building blocks shown. Our research typically focuses on the contents of these blocks, including the environmental effects

Source: Know-How Base Description (Blacquiere)







Sonar expertise at TNO

"We know how to detect, classify and localize underwater threats like mines, torpedoes and submarines in the dynamic underwater environment,

and how to realize complete systems together with international partners"

- Staff description in keywords:
- Large technological expertise
- Excellent relation with RNLN
- International recognition
- Expertise working at sea
- Currently 37 employees
- Large number of PhD's (18)



TNO magazine interviewed two project

leaders at the NL MOD in 2007.







Current UWW research programmes & projects

- V931 Environment and underwater RMP (the effect of the complex underwater environment on sonar system performance)
- V932 Underwater systems and threat (research on underwater sensorprocessing and weapon systems for own units, threats and unmanned
- V1026 Environmental effects of sonar systems V1206 MCM operations with AUV's
- V1210 Coordinated deployment of underwater sensors

Contracts for MOD-NL, EDA and Industry: EDA RACUN (UWCOMMS), MAPS, MANTA, EDA Siramis, FATA, SAKAMATA, MUD, APPROXA,







V931 Environment and underwater picture compilation

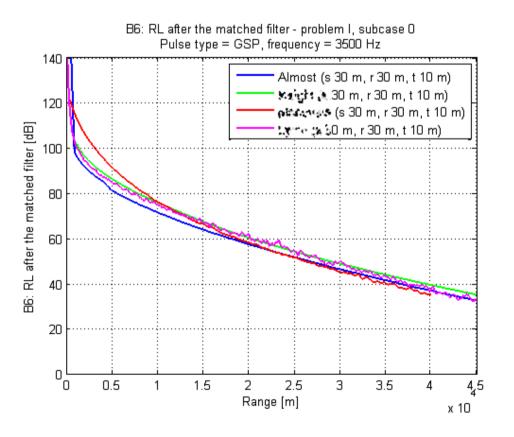
- Military oceanography; oceanographic modelling and integration with acoustics
- Acoustic environment, range dependent acoustic propagation, sea surface and bubble influence, automatic bottom classification
- Sensor innovations and advanced processing; Technology watch on sensors for autonomous systems, automatic target recognition and high-resolution SAS, Detection of buried mines
- Environmental effects of sonar (regulations)

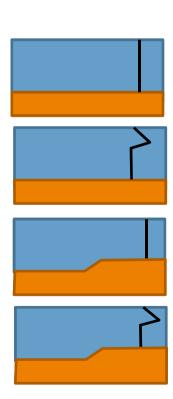






International collaboration to define benchmarks and compare different models











V932 Underwater systems and threat

Research on underwater sensor- processing and weapon systems for

own units, threats and unmanned systems

- Future ASW sensors
- Torpedo DCL
- Wideband techniques
- **Trials**



Hr.Ms. Van Amstel test prototype sonarsysteem

WILLEMSTAD Hr.Ms. Van Amstel heeft vorige week nabij Curação een geslaagde Torpedo Firing Exercise uitgevoerd met. een prototype van een nieuw sonarsysteem.

Doelvan de oefening was het beproeven lende inzetmodes af op het fregst. Het wan een nieuwe turpedodetectie aan. sonamynteem opereerde hierbij Boord van de Van Amstel. Het fregat zette - tegefijkertijd in actieve en in passieve celening om de presisties van de exercitiesorpedo's te evalueres en de eigen boordheldopterbemanning gettstind te houden in het lanceren van volgen. Deze door TNO-ontwikkelde norpedo's.

Van Amonel diende in de test als doelschip. De Izex boonfhelikopser vuunde wif NK₄6 exercitiesorpedo's in verschil-

het prototype laughtsquent actieve status om 20 de torpedo te detectoren en sonamysteem (IRLEAS) in. Ook diende de - te volgen. Gedunende iedere test was de Yon Amond met hour sonomysteem in stact om op ruime afstand van het schip de torpedo te detecteren en continu te sonamenteem zal vanuf 2013 worden toepepast zan boord van de M-fregutsen. Het hulpschip Ht Ms. Pelikaun assistmente bij het oppikken van de torpedo's.







V1026 Environmental effects of sonar systems

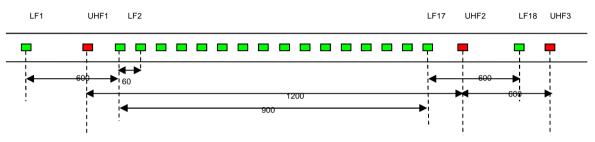
- Develop acoustic detection, classification and localisation
- Effect of sonar on eco systems (by contribution to controlled exposure experiments with FFI, SMRU and WHOI)
- Analysis of results and reporting
- Advice for implementation in SAKAMATA





PAM & DCL – The Delphinus system

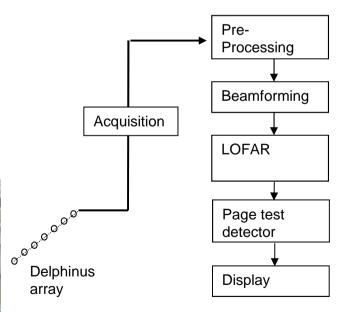
Operation depth: 30 - 200m



- > Delphinus Wet end
 - > 700 m tow cable
 - Delphinus Processing:
 - Pre-processing and beamforming,
 - > Real-time automatic transient detection,
 - Localisation
 - Audio and spectral analysis













The 3S trials



















V1210 Coordinated deployment of underwater sensors

- Development of an Acoustic Support Roadmap
- Architectural design of future Multi-Use Acoustic Support Suite
- A Priori planning of underwater operations
- In Situ planning of underwater operations
- International collaboration

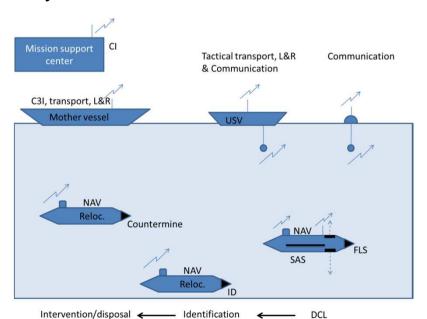






V1206 MCM operations with AUV's

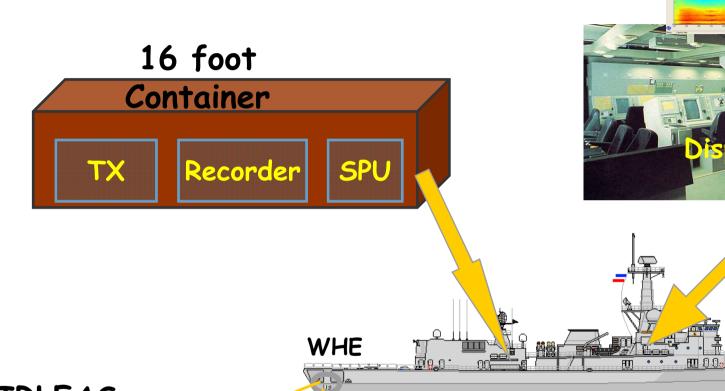
- Autonomous object assessment (DCL)
- > Environment assessment
- Navigation and obstacle avoidance
- Situational awareness and autonomy
- System design and evaluation







IRLFAS Technology Demonstrator





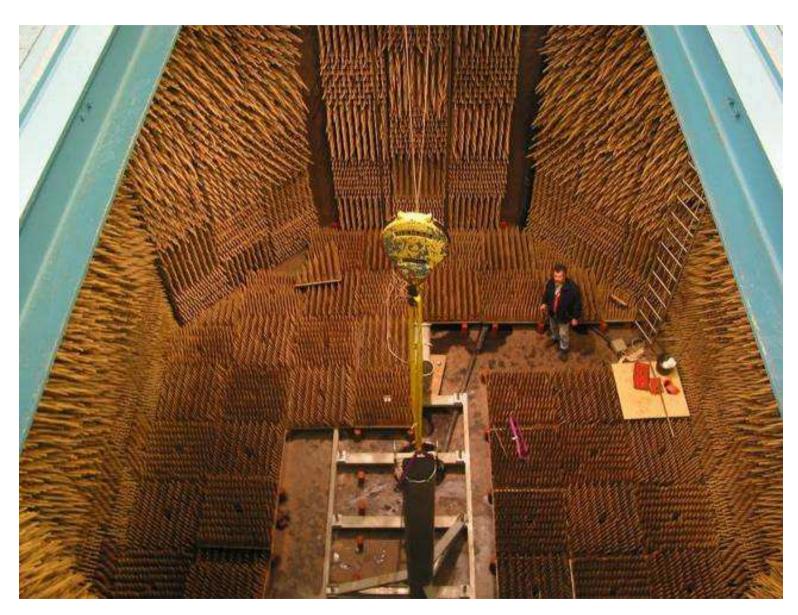


M-Frigate













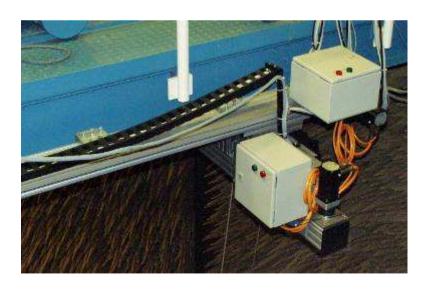
Anechoic basin



Signatures, near field measurements



- **>** Basin: 8x10x8 m
- Turntable for measurement of directivity pattern
- > Scanframe: 6x4 m, 0.1 mm









Anechoic basin scanframe

- > Scansurface 6 m x 4 m
- Precision positioning 0.1 mm
- Scale model measurements
- Near field measurements (acoustic imaging/holography)

